Xingpeng Sun

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	DUCATION	
Pu	rdue University	08/2023-05/2028
Do	ctor of Philosophy in Computer Science	West Lafayette, IN
•	Research Interest: Embodied AI, Robotics, Graphics, LLM/VLM, Generative AI	
•	Advisor: Dr. Aniket Bera	
	iversity of Wisconsin-Madison	09/2019-12/2022
Bad	<i>chelor of Science</i> Majors: Computer Science (Distinction in Major), Mathematics	Madison, WI
•	GPA: 3.97/4.00; Graduated with Distinctive Scholastic Achievement, Dean's List (6	semesters)
PU	BLICATION	
•	TrustNavGPT: Trust-Driven Audio-Guided Robot Navigation under Uncertainty w Models	vith Large Language IROS 2024 (Oral)
	Xingpeng Sun, Yiran Zhang, Xindi Tang, Amrit Singh Bedi, Aniket Bera	
•	DL3DV-10K: A Large-Scale Scene Dataset for Deep Learning-based 3D Vision	CVPR 2024
PR	EPRINT UNDER REVIEW	
•	LLM-guided UAV Trajectory Generation	
	Xingpeng Sun , Zherong Pan, Xifeng Gao, Kui Wu, Aniket Bera	
•	Beyond Text: Improving LLM's Decision Making for Robot Navigation via Vocal	Cues
	Xingpeng Sun, Haoming Meng, Souradip Chakraborty, Amrit Singh Bedi, Aniket	
•	Efficient EQA: An Efficient Approach for Open Vocabulary Embodied Question A	
RE	CSEARCH EXPERIENCE	
Lig	ghtspeed Studios, Tencent America	06/2024 - 08/2024
Res	search Intern Mentor: Dr. Zherong Pan, Dr. Xifeng Gao, Dr. Kui Wu	Bellevue, WA
•	Developed a novel zero-shot UAV trajectory generation method guided by text-ba	· · · · ·
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•		sed large language
•	models (LLMs), enabling drones to follow human navigation commands and exect	sed large language ute time-optimal,
•	models (LLMs), enabling drones to follow human navigation commands and exect smooth flights in complex large 3D environments; work submitted to ICRA 2025.	sed large language ute time-optimal, rves injectivity for
	models (LLMs), enabling drones to follow human navigation commands and exect smooth flights in complex large 3D environments; work submitted to ICRA 2025. Designed the first text-guided mesh biharmonic deformation algorithms that prese	sed large language ute time-optimal, rves injectivity for
ID	models (LLMs), enabling drones to follow human navigation commands and exect smooth flights in complex large 3D environments; work submitted to ICRA 2025. Designed the first text-guided mesh biharmonic deformation algorithms that prese deformable editing of 3D assets by leveraging image language foundation models.	sed large language ute time-optimal, rves injectivity for
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Frameworks/Tools: TensorFlow, PyTorch, OpenCV, React, Git, Blender, Figma, MySQL, AWS

HONORS and AWARDS

Conference Reviewer: IROS, ICRA, SIGGRAPH ASIA, PACIFIC GRAPHIC